Minimizing convex functions over integer points

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Let
$$f : [0,T] \to \mathbb{R}$$
 be a given function (signal)
 $g : \mathbb{R} \to \mathbb{R}$ be another given function (filter)
with $g(t) = 0$ for $t \le 0$
 $\delta := T/n$, where $n \in \mathbb{Z}_{++}$ (time-step)

We want to approximate f as well as possible by

$$\widehat{f}_x(t) := \sum_{i=1}^n x_i g(t - (i - 1)\delta), \text{ with } x_i \in \{0, 1\}.$$

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$$\Leftrightarrow \min\{x^{T}Qx + 2c^{T}x + d : x \in \{0, 1\}^{n}\}$$

$$Q_{ij} = \int_{0}^{T} g(t - (i - 1)\delta)g(t - (j - 1)\delta)dt, c_{i} = \int_{0}^{T} g(t - (i - 1)\delta)f(t)dt$$

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► We have a convex objective with binary variables.

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$$\star \mathcal{F} = P \cap \mathbb{Z}^n$$
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where P is a polytope;

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 \boldsymbol{x}^* can be arbitrarily far from the continuous minimum

A way to measure how hard our problem is

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* $\mathcal{F} = P \cap \mathbb{Z}^n$, where P is a polytope; * $f : \mathbb{R}^n \to \mathbb{R}$ is convex.

We assume that f is strongly convex and L-smooth: for every $x, y \in \mathbb{R}^n$:

$$\frac{l}{2}||x-y||_2^2 \le f(y) - f(x) - f'(x)^T(y-x) \le \frac{L}{2}||x-y||_2^2.$$

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L/l bounds the asphericity of level sets.
 A trivial enumeration algorithm would take
 O(min{(L/l)ⁿ, diameter(F)ⁿ}) evaluations of f.

▶ In fact, the complexity of our methods depends on L - l.

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- ► Even with *f* linear, the problem is **NP-Hard**
- ► Even with f quadratic and $\mathcal{F} \subseteq \{0, 1\}^n$, the problem is **hard**, independently of the NP-Conjecture.

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- \blacktriangleright Even with f linear, the problem is **NP-Hard**
- Even with f quadratic and F ⊆ {0,1}ⁿ, the problem is hard, independently of the NP-Conjecture. Consider n = 4m, c ∈ {2,3}, γ = 5m − 1, F ⊆ {0,1}ⁿ be an independence system, and

$$\min\{f(x) = n^2(c^T x - \gamma)^2 + \mathbf{1}^T x : x \in \mathcal{F}\}.$$

 \mathcal{F} is presented by an LP solver:

taking as input $v \in \mathbb{R}^n$, returns $\arg \max_{x \in \mathcal{F}} v^T x$. Note: We have $L/l \leq 9n^3 + 1$.

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Theorem 1 Any method that solves less than $\binom{2m}{m+1} \ge 2^m$ LPs on \mathcal{F} fails to find an \hat{x} for which $f(\hat{x}) - f(x^*) \le n^2 - n$.

Very few methods exist for our problem

$$f(x^*) := \min_{x \in \mathcal{F}} f(x)$$

* $\mathcal{F} = P \cap \mathbb{Z}^n$, where P is a polytope; * $f : \mathbb{R}^n \to \mathbb{R}$ is convex.

- Branch and bound approach (Gupta, Ravindran, Leyffer) Branching by fixing some variables.
 Lower bounds from continuous relaxation of all the other ones, with possibly extra cuts
- 2. Outer Approximation (Duran, Grossman)
 (assumes that we can solve the problem with f linear)
 f is replaced by a piecewise linear model,
 which is minimized in F, then enriched.

Our methods use simple ideas from Convex Optimization

$$f(x^*) := \min_{x \in Q} f(x)$$

- ★ $Q \subseteq \mathbb{R}^n$ is convex and closed;
- $\star f : \mathbb{R}^n \to \mathbb{R}$ is convex.

Subgradient method:

Select $x_0 \in Q$ for k = 0, 1, 2, ...Choose $h_k > 0$, compute $f'(x_k) \in \partial f(x_k)$ Set $x_{k+1} := \pi_Q(x_k - h_k f'(x_k))$ $= \arg \min_{y \in Q} \left\{ f'(x_k)(y - x_k) + \frac{1}{2h_k} ||y - x_k||_2^2 \right\}.$

• Guaranteed decrease with $h_k = 1/L$, theoretically the best choice.

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Gradient method:

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Our strategy:

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- ▶ We allow for a step-size τ larger than 1/L.
- ► This quadratic problem can be very hard to solve exactly
- ► $x_{k+1} \in \mathcal{F}$ and $g_{x_k}(x_{k+1}) \leq (1-\alpha) \min_{y \in \mathcal{F}} g_{x_k}(y) < 0$,

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If we don't move anymore, we are done

Select $x_0 \in \mathcal{F}$, $0 \leq \alpha < 1$, $l \leq \tau \leq L$, $N \in \mathbb{Z}_+$ for $k = 0, 1, \dots, N - 1$, Compute x_{k+1} such that $g_{x_k}(x_{k+1}) \leq (1 - \alpha) \arg \min_{y \in \mathcal{F}} g_{x_k}(y)$ if $x_{k+1} \in \{x_0, \dots, x_k\}$ STOP return the best $\hat{x} \in \{x_0, \dots, x_N\}$.

Theorem 2 If $\tau = 1/l$ and $x_{k+1} = x_k$, then $f(x_k) = f(x^*)$.

Our method can solve the problem approximately

Select $x_0 \in \mathcal{F}$, $0 \leq \alpha < 1$, $1/L \leq \tau \leq 1/l$, $N \in \mathbb{Z}_+$ for $k = 0, 1, \dots, N - 1$, Compute x_{k+1} such that $g_{x_k}(x_{k+1}) \leq (1 - \alpha) \arg \min_{y \in \mathcal{F}} g_{x_k}(y)$ if $x_{k+1} \in \{x_0, \dots, x_k\}$ STOP

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Theorem 3 If $\alpha > 0$, $\eta > 0$, $\delta_{\mathcal{F}} = diameter(\mathcal{F})$ and

$$N := \left\lceil \frac{1}{\ln(1/\alpha)} \ln \left(\max \left\{ 1, \frac{f(x_0) - f(x^*)}{\eta} \right\} \right) \right\rceil,$$

then
$$f(\hat{x}) - f(x^*) \leq \frac{L-l}{2(1-\alpha)}\delta_{\mathcal{F}}^2 + \eta.$$

The subproblem can sometimes be solved

We know: quadratic problems on \mathcal{F} can be **hard**

Theorem 4 (Heinz) We can solve the subproblem exactly ($\alpha = 0$) in $s^{\mathcal{O}(1)}2^{\mathcal{O}(n)}$ arithmetic operations, where s is its binary encoding length.

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Theorem 4 (Heinz) We can solve the subproblem exactly ($\alpha = 0$) in $s^{\mathcal{O}(1)}2^{\mathcal{O}(n)}$ arithmetic operations, where s is its binary encoding length.

- ▶ If F ⊆ {0,1}ⁿ, the subproblem is linear (as x_i² = x_i).
 We can solve it efficiently for classes of problems where IP is easy (e.g. matroid problems, matchings)
- ▶ Many quadratic problems admit a fast approximate method with guaranteed α . (e.g. binary knapsack problems)

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However, we can get a previously visited point *(cycling)* Remedy: Assume $f(x) \in \mathbb{Z}$ for $x \in \mathcal{F}$ and set $\tau = 1/l$. Instead of computing min $\{g_{x_k}(x) : x \in \mathcal{F}\}$, do:

$$\min\{g_{x_k}(x) : g_{x_i}(x) \le -1 \text{ for } 0 \le i \le k, x \in \mathcal{F}\}$$

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• Computes
$$x^*$$
 in $\mathcal{O}(c_f(L-l)\delta_{\mathcal{F}}^2 s^{\mathcal{O}(1)})$,
where $c_f = \max_{\alpha \in \mathbb{Z}} |\mathcal{F} \cap \{x : f(x) = \alpha\}|$.

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- ▶ Modest, but can be better than an enumeration $(\mathcal{O}(\delta_{\mathcal{F}}^n))$.

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- ► Never generates twice the same point
- Subproblems polynomially solvable for some well-structured binary problems (e.g. when *F* ⊆ {0,1}ⁿ is a vectorial matroid)

Conclusion and outlook 1

- ► The field is almost new.
- Convex integer problems are intrinsically hard.
- Our methods provide polynomial algorithms for instances where quadratic problems can be easily minimized on their feasible set.
- We have complexity and accuracy guarantees when quadratic functions can only be solved approximately.
- ► The mixed-integer case remains largely unaddressed

Conclusion and outlook 2

- We are developing new methods based on the existence of a *level set oracle*: Fix $\alpha \ge 0$, $\delta \ge 0$. For every $x \in \mathbb{R}^n$, the oracle finds $\hat{x} \in \mathbb{Z}^n$ such that $f(\hat{x}) \le (1 + \alpha)f(x) + \delta$, or declares it does not exists.
- ► They can be extended to general lattices.
- ► They allow us to solve 2 dim. problems polynomially in ln(L/l).
- They seem promising to attack mixed-integer convex problems.

Thank you